Assessment proposed by the supervisor of Master 's thesis: **Very good**
Assessment proposed by the reviewer of Master 's thesis: **Good**

Course of the defence:

Ing. Miloš Šikola, MBA
How do you solve the issue of point ambiguousness?
Answered partially
Ing. Petr Zelený, Ph.D.
What was the main task in master thesis? What was your own contribution?
Answered partially
prof. Ing. Přemysl Pokorný, CSc.
Do you change the path of robot online? What is time delay of your control system? How did you choose the calculation method?
Answered partially
prof. Ing. Stanislav Hosnedl, CSc.
Is there a possibility to replace the effector that you used in your control system?
Answered
How can you guarantee satisfactory gripping of the used effector?
Didn' t answer

Assessment: **Very good minus**

Defence date: June 12, 2018   . . . .
                                                              Committee Chairperson's signature